# DISTRIBUTED MINING OF ASSOCIATION RULES

# CROSS-REFERENCE TO RELATED APPLICATION

This application claims the benefit of U.S. Provisional Patent Application 60/271,165, filed February 23, 2001, which is incorporated herein by reference.

# FIELD OF THE INVENTION

The present invention relates generally to database mining, and specifically to discovery of association rules in large transactional databases.

### BACKGROUND OF THE INVENTION

Association Rule Mining (ARM) in large transactional databases is a central problem in the field of knowledge discovery. The input to the ARM is a database in which objects are grouped by context. An example of such a grouping would be a list of items grouped by the customer who bought them. ARM then finds sets of objects which tend to associate with one another. Given two distinct sets of objects, X and Y, we say Y is associated with X if the appearance of X in a certain context usually implies that Y will appear in that context as well. If X usually implies Y, we then say that the rule  $X \Rightarrow Y$  is confident in the database.

Typically, an association rule is of practical interest only if it appears in more than a certain number of contexts. If it does, we say that the rule is frequent, i.e., that it has a large support. The thresholds of support (MinSup) and confidence (MinConf) are parameters that are used to define which association rules are of interest. These parameters are usually supplied by the user according to his needs and

resources. The solution to the ARM problem is a list of all association rules that are both frequent and confident in that database. Such lists of rules have many applications in the context of understanding, describing and acting upon the database.

A variety of algorithms have been developed for ARM. Such algorithms are described, for example, by Agrawal and Srikant in "Fast Algorithms for Mining Association Rules," Proceedings of the 20th International Conference on Very Large Databases (VLDB94 - Santiago, Chile, 1994), pages 487-499, which is incorporated herein by reference. It has been shown that the major computational task in ARM is the identification of all the frequent itemsets, i.e., those sets of items which appear in a fraction greater than MinSup of the transactions. Association rules can then be produced from these frequent itemsets in a straightforward manner. For example, once it is known that both (Pasta Sauce) and (Pasta Sauce, Parmesan) are frequent itemsets, the association rule { Pasta Sauce} ⇒ (Parmesan) is obviously frequent, and all that remains check whether the association is confident. Because databases are often very large and are typically stored in secondary memory (disk), ARM algorithms known in the art are mainly concerned with reducing the number database scans required to arrive at the desired collection of frequent itemsets, and hence to determine the confident association rules.

In the above-mentioned paper, Agrawal and Srikant describe an ARM algorithm that they call "Apriori." The algorithm begins by assuming that any item is a candidate to be a frequent itemset of size k=1. Apriori then

performs several rounds of a two-phased computation. In the first phase of the kth round, the database is scanned, and support counts are calculated for all k-size candidate itemsets. Those candidate itemsets that have support above the user-supplied MinSup threshold are considered frequent itemsets. In the second phase, candidate k+1-size itemsets are generated from the set of frequent k-size itemsets if and only if all their k-size subsets are frequent. The rounds terminate when the set of frequent k-size itemsets is empty.

In Distributed Association Rule Mining (D-ARM), the ARM problem is restated in the context of distributed In D-ARM, the database is partitioned among computing. several nodes that can perform independent parallel computations, as well as communicate with one another. A number of algorithms have been proposed to solve the D-ARM problem, particularly for share-nothing machines (i.e., distributed computing systems in which each node uses its own separate memory). An exemplary D-ARM algorithm is described by Agrawal and Shafer in "Parallel Mining of Association Rules," IEEE Transactions on Knowledge and Data Engineering 8:6 (1996), pages 962-969, which is incorporated herein by reference. D-ARM has a major advantage over conventional ARM. in that parallelizes disk I/O operations. The main difficulty for D-ARM algorithms is communication complexity among the nodes. The most important factors the communication complexity of D-ARM algorithms aro the number of partitions (or computing nodes), n, and the number of itemsets, |C|, considered by the algorithm.

Agrawal and Shafer present two major approaches to D-ARM: data distribution (DD) and count distribution

(CD). DD focuses on the optimal partitioning of database in order to maximize parallelism. CD, on the other hand, considers a setting in which the data are arbitrarily partitioned horizontally among the parties to begin with, and focuses on parallelizing the computation. (Horizontal partitioning means that each partition includes whole transactions, in contrast with vertical partitioning, in which the same transaction is split among several parties.) The DD approach is not always applicable, since at the time the data are generated, they are often already partitioned. In many cases, the data cannot be gathered and repartitioned for reasons of security and secrecy, cost of transmission, or efficiency. DD is thus more applicable to systems that are dedicated to performing D-ARM. CD, on the other hand, is typically a more appealing solution for systems that are naturally distributed over large expanses, such as stock exchange and credit card systems.

The CD algorithm presented by Agrawal and Shafer is a parallelization of the Apriori algorithm described above. In the first phase of CD, each of the nodes performs a database scan independently on its partition. Then the nodes exchange their scan results, and a global sum reduction is performed on the support counts of each candidate itemset. Those itemsets whose global support is larger than MinSup are considered The second phase, calculating the candidate frequent. k+1-size itemsets, can be carried out without communication, because the calculation depends only on the identity of the frequent k-size itemsets, which is known to all parties by this time. Thus, CD parallelizes the disk I/O complexity of Apriori

performs roughly the same computations. CD also requires one synchronization point on each round and carries an  $O(|C|\cdot n)$  communication complexity penalty. Since typical values for |C| are tens or hundreds of thousands, CD is not scalable to large numbers of partitions.

In order to reduce this communication load, Cheung et al. introduced the FDM algorithm, in Distributed Algorithm for Mining Association Rules," Proceedings of the 1996 International Conference on Parallel and Distributed Information Systems Beach, Florida, 1996), pages 31-44, which is incorporated herein by reference. FDM takes advantage of the fact that ARM algorithms look only for rules that are globally frequent. FDM is based on the inference that in order for an itemset to appear among all the transactions in the database with a given frequency, there must be at least one partition of the database in which the itemset appears at the given frequency or greater. Therefore, in FDM, the first stage of CD is divided into two rounds of communication: In the first round, every party names those candidate itemsets that are locally frequent in its partition (because they appear in the partition with a frequency greater than or equal to MinSup/|database|). In the second round, counts are globally summed only for those candidate itemsets that were named by at least one party. If the probability that an itemset will have the potential of being frequent is Prpotential, then FDM only communicates Prporential | C | of the itemsets. Ιt improves the communication complexity to O(Prpotential- | C | -n) .

FDM is problematic when large numbers of nodes are involved in the computation, because Protential is not scalable in n, and quickly increases to 1 as n increases, particularly in inhomogeneous databases. This problem was pointed out by Cheung and Xiao in "Effect of Data Skewness in Parallel Mining of Association Rules," Second Pacific-Asia Conference of Knowledge Discovery and Data Mining (1998), pages 48-60, which is incorporated herein reference. The authors show that inhomogeneity of the database increases, FDM pruning techniques become ineffective.

Over the past few years, distributed information systems have become a mainstream computing paradigm, and the wealth of information available in these systems is constantly expanding. Examples of distributed information resources of this sort include a company's Virtual Private Network, a multi-server billing center, a network of independent stockbrokers, and a peer-to-peer MP3 library, such as Napster™. There is a growing need for tools that can assist in understanding and describing such information. These new databases differ distributed databases of the past, that the partitioning ΟÎ the data is usually skewed, the connections between partitions are sparse and often unreliable, and variable throughputs and latencies may apply to different nodes. characteristics These accentuate the inadequacies of D-ARM methods known in the art.

### SUMMARY OF THE INVENTION

It is an object of the present invention to provide improved methods for Distributed Association Rules Mining (D-ARM).

It is a further object of some aspects of the present invention to provide D-ARM methods with reduced communication complexity.

It is yet a further object of some aspects of the present invention to provide D-ARM methods that are robust in the face of database skew and inhomogeneity.

In preferred embodiments of the present invention, a data mining system comprises a plurality of computing nodes, each node having a local memory that contains a respective partition of a distributed database. The nodes are mutually connected by a network, which enables all the nodes to transmit and receive messages one to another, preferably broadcast messages. The cooperatively calculate the set of candidate itemsets whose support exceeds a predetermined minimum, preferably using an Apriori-type iterative algorithm, as described above, wherein after all the k-size itemsets have been determined, they are used to find the k+1-size itemsets.

At each stage in the calculation (i.e., for each value of k), each node broadcasts support counts of itemsets that it believes to be frequent over the entire database. Unlike algorithms known in the art, such as FDM, however, in preferred embodiments of the present invention, the fact that an itemset is locally frequent in one partition is not considered sufficient evidence to trigger collection of all the support counts of the itemset from all the nodes. Rather, the choice of which itemsets to broadcast is based on dynamic candidacy

criteria, indicating which itemsets are likely to be globally frequent. The global support counts criteria of the itemsets are recalculated asynchronously by each of the nodes, based on the messages it has received from the other nodes. The nodes continue to broadcast the support counts οf possible candidate itemsets and to update the candidacy criteria accordingly, until all the nodes have agreed on the same set of globally-frequent candidates. Only after this point do all nodes broadcast their support counts for the agreed-upon candidates, if they have not yet done so.

Preferred embodiments of the present invention thus reduce the communication complexity of D-ARM algorithms, by avoiding wasted communications on itemsets that are locally frequent but globally infrequent. It can be shown that the methods of the present invention have a communication complexity that is linear in the number of partitions (or nodes) n and in the number of itemsets |C|, with a very small database-dependent multiplicative factor, much smaller than the  $Pr_{potential}$  multiplier of the FDM method. Even for moderate values of n, these methods require only a fraction of the communication bandwidth used by methods known in the art. Therefore, bandwidth-limited systems, the methods of the present invention enable association rules to be mined with superior efficiency and speed.

There is therefore provided, in accordance with a preferred embodiment of the present invention, a method for mining association rules in a database that is divided into multiple partitions associated with respective computing nodes, the method including:

transmitting messages among the nodes with respect to local support of an itemset in the respective partitions of the database;

responsive to the messages transmitted by a subset of the nodes, determining the itemset to be globally frequent in the database before the nodes outside the subset have transmitted the messages with respect to the local support of the itemset in their respective partitions; and

computing an association rule with respect to the itemset, responsive to having determined the itemset to be globally frequent.

Preferably, transmitting the messages includes conveying the messages over a communication network connecting the nodes one to another. Most preferably, conveying the messages includes broadcasting messages. Additionally or alternatively, conveying the messages includes stacking a plurality of the messages together in a single data frame for transmission over the network.

Preferably, transmitting the messages computing a candidacy criterion at each of the nodes, for in determining whether the itemset is frequent, and choosing the itemset with respect to which one of the messages is to be transmitted responsive to the candidacy criterion. Most preferably, computing the candidacv criterion includes receiving one messages sent by another one of the nodes, and recomputing the candidacy criterion responsive to the local support conveyed by the received message, wherein itemset includes choosing the deciding whether transmit another one of the messages with respect to the

itemset based on the recomputed criterion. Further preferably, deciding whether to transmit another one of the messages includes transmitting another one of the messages only until a conclusion is reached, responsive to the candidacy criterion, as to whether the itemset is globally frequent in the database. Additionally or alternatively, transmitting the messages includes terminating transmission of the messages when candidacy criterion computed at every one of the nodes agrees as to whether the itemset is globally frequent.

Typically, the itemset is one of a plurality of itemsets in the database, and computing the candidacy criterion includes computing respective criteria for the plurality of the itemsets, choosing the itemsets includes ranking the itemsets responsive to the respective candidacy criteria transmission of the messages with respect thereto. preferred embodiment, ranking the itemsets determining a respective ranking for each of the nodes, and transmitting the messages includes selecting one of the nodes that is to transmit the messages, responsive to the respective ranking. Preferably, determining the respective ranking includes updating the ranking as the messages are transmitted, and selecting the one of the nodes includes changing a selection of the one of the nodes that is to transmit the messages responsive to a change in the ranking.

Preferably, computing the association rule includes collecting the local support of the itemset from the nodes outside the subset, for use in computing the association rule applicable to the itemset, only after it is determined that the itemset is globally frequent.

Typically, the itemset is one of a plurality of itemsets in the database, and collecting the local support includes collecting the local support of the itemsets that were determined to be globally frequent, while ignoring the local support of the itemsets that were not determined to be globally frequent.

In a preferred embodiment, computing the association rule includes assessing a confidence level of the rule responsive to the local support, and collecting the local support includes computing a confidence criterion at each the nodes, for use in determining whether confidence level is above a predetermined threshold, and choosing the itemset with respect to which the local support is to be collected responsive to the confidence criterion. Preferably, computing the confidence criterion includes receiving the local support sent by another one of the nodes, and recomputing the confidence criterion responsive to the received local support, wherein choosing the itemset includes continuing to collect the local support until it is determined that the confidence level is above the predetermined threshold, based on the recomputed criterion.

Typically, the itemset is one of a plurality of itemsets in the database, each of the itemsets having a size, and determining the itemset to be globally frequent includes finding the itemsets of size k that are globally frequent, and transmitting the messages includes transmitting the messages with respect to the local support of the itemsets of size k+1 all of whose subsets are itemsets of size k that were found to be globally frequent.

There is also provided, in accordance with a preferred embodiment of the present invention, a method for mining association rules in a database that is divided into multiple partitions associated with respective computing nodes, the partitions including at least first and second partitions respectively associated with at least first and second nodes among the computing nodes, the method including:

computing an initial candidacy criterion at each of the nodes, for use in determining whether an itemset is globally frequent in the database;

responsive to the candidacy criterion, transmitting a first message from the first node to the other nodes conveying a local support of the itemset in the first partition;

upon receiving the message, recomputing the candidacy criterion at the second node responsive to the local support conveyed by the message;

transmitting, responsive to the recomputed candidacy criterion, a second message from the second node to the other nodes, conveying the local support of the itemset in the second partition; and

computing an association rule with respect to the itemset, responsive to the first and second messages.

Typically, the nodes further include a third node, and the method includes recomputing the candidacy criterion at the third node, responsive to the first and second messages, and determining at the third node that the itemset is globally frequent based on the recomputed criterion. Preferably, determining at the third node that the itemset is globally frequent includes making a conclusive determination that the itemset is globally

frequent before all the nodes have transmitted messages conveying the local support of the itemset the respective partitions οf the database. preferably, computing the association rule includes computing the rule responsive to baving determined that the itemset is globally frequent based on the recomputed criteria.

Preferably, computing the initial candidacy criteria includes computing at each of the first and second nodes a local hypothesis as to whether the itemset is globally frequent, based on the local support of the itemset in the first and second partitions, respectively, recomputing the candidacy criterion includes recomputing the local hypothesis and computing a global hypothesis as to whether the itemset is globally frequent, based on the local support conveyed in the first message, transmitting the second message includes deciding whether to transmit the second message responsive to the local and global hypotheses. Most preferably, deciding whether to transmit the second message includes deciding to transmit the second message only if the local and global hypotheses computed at the second node disagree as to whether the itemset is globally frequent.

Typically, the itemset is one of a plurality of itemsets in the database, and computing and recomputing the candidacy criterion include computing and recomputing respective local and global hypotheses for the plurality of the itemsets, and transmitting the first and second messages includes choosing the itemset with respect to which the messages are to be transmitted responsive to the respective hypotheses. In a preferred embodiment, choosing the itemset includes ranking the itemsets

responsive to a measure of disagreement between the local and global hypotheses with respect to the itemsets. Preferably, deciding whether to transmit the second message includes, if none of the local and global hypotheses disagree, transmitting a pass message.

There is additionally provided, in accordance with a preferred embodiment of the present invention, apparatus for mining association rules, including:

a plurality of storage devices, adapted to hold respective partitions of a database; and

a corresponding plurality of computing nodes, each node being associated with a respective one of storage devices and coupled to communicate with the other nodes over a communication network, the nodes being adapted to transmit messages one to another with respect local support of an itemset in the respective partitions of the database, and responsive to messages transmitted by a subset of the nodes, to determine the itemset to be globally frequent in the database before the nodes outside the subset transmitted the messages with respect to the support of the itemset in their respective partitions, and to compute an association rule with respect to the itemset, responsive to having determined the itemset to be globally frequent.

There is further provided, in accordance with a preferred embodiment of the present invention, apparatus for mining association rules, including:

a plurality of storage devices, adapted to hold respective partitions of a database, including at least first and second storage devices holding respective first and second partitions of the database; and

a corresponding plurality of computing nodes, each node being associated with a respective one of storage devices. including at least first and second nodes respectively associated with the first and second storage devices, the nodes being coupled to communicate with one another over a communication network, the nodes further being adapted to compute an initial candidacy criterion, for use in determining whether an itemset is globally frequent in the database, such that responsive the candidacy criterion, the first transmits a first message to the other nodes conveying a local support of the itemset in the first partition, and such that upon receiving the message, the second node recomputes the candidacy criterion responsive to the local support conveyed by the message and transmits, responsive to the recomputed candidacy criterion, second message from the second node to the other nodes. conveying the local support of the itemset in the second partition, so that the nodes compute an association rule with respect to the itemset responsive to the first and second messages.

There is moreover provided. in accordance with a preferred embodiment of the present invention, a computer software product, including a computer-readable medium in wliach program instructions are stored, which instructions, when read by computing nodes that associated with respective storage devices respective partitions of a database and are coupled to communicate with one another over а communication network, cause the nodes to transmit messages one to another with respect to local support of an itemset in the respective partitions of the database, and responsive

to the messages transmitted by a subset of the nodes, to determine the itemset to be globally frequent in the database before the nodes outside the subset have transmitted the messages with respect to the local support of the itemset in their respective partitions, and to compute an association rule with respect to the itemset, responsive to having determined the itemset to be globally frequent.

There is furthermore provided, in accordance with a preferred embodiment of the present invention, a computer software product, including a computer-readable medium in which program instructions are stored, instructions, when read by computing nodes that associated with respective partitions of a database, including at least first and second nodes respectively associated with first and second partitions database, and which are coupled to communicate with one another over a communication network, cause the nodes to compute an initial candidacy criterion, for use determining whether an itemset is globally frequent in the database, and responsive the candidacy criterion, cause the first node to transmit a first message to the other nodes conveying a local support of the itemset in the first partition, and cause the second node, upon receiving the message, CO recompute the criterion responsive to the local support conveyed by the message and to transmit, responsive to the recomputed candidacy criterion, a second message to the other nodes, conveying the local support of the itemset in the second partition, and cause the nodes to compute an association rule with respect to the itemset responsive to the first and second messages.

There is also provided, in accordance with a preferred embodiment of the present invention, a method for processing items in a database that is divided into multiple partitions associated with respective computing nodes, the method including:

transmitting messages among the nodes conveying local information regarding an itemset in the respective partitions of the database;

responsive to the messages transmitted by a subset of the nodes, determining the itemset to be globally significant with respect to a decision to be made in reference to the database before the nodes outside the subset have transmitted the messages with respect to the local information regarding the itemset in their respective partitions; and

making the decision with respect to the itemset, responsive to having determined the itemset to be globally significant.

There is additionally provided, in accordance with a preferred embodiment of the present invention, a method for reaching a decision regarding items in a database that is divided into multiple partitions associated with respective computing nodes, the partitions including at least first and second partitions respectively associated with at least first and second nodes among the computing nodes, the method including:

computing an initial candidacy criterion at each of the nodes, for use in selecting an itemset in the database of potential significance to the decision;

responsive to the candidacy criterion, transmitting a first message from the first node to the other nodes

conveying local information regarding the itemset in the first partition;

upon receiving the message, recomputing the candidacy criterion at the second node responsive to the local information conveyed by the message;

transmitting, responsive to the recomputed candidacy criterion, a second message from the second node to the other nodes, conveying the local information regarding the itemset in the second partition; and

making the decision with respect to the itemset, responsive to the first and second messages.

Preferably, computing the initial candidacy criterion includes determining the candidacy criterion based on a target function selected responsive to the decision that is to be made.

The present invention will be more fully understood from the following detailed description of the preferred embodiments thereof, taken together with the drawings in which;

## BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a schematic, pictorial illustration of a system for distributed association rule mining (D-ARM), in accordance with a preferred embodiment of the present invention:

Figs. 2A and 2B are flow charts that schematically illustrate a method for D-ARM, in accordance with a preferred embodiment of the present invention;

Figs. 3A-D, 4A-D and SA-D are bar charts, that schematically illustrate successive stages encountered in carrying out the method of Figs. 2A and 2B on an exemplary database; and

Figs. 6A and 6B are flow charts that schematically illustrates a method for D-ARM, in accordance with another preferred embodiment of the present invention.

#### DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

#### NOTATION

Let  $I = \{i_1, i_2, ..., i_n\}$  be the set of items in the database to be mined. A transaction t is a subset of I. Let DB be a list of D such transactions. Let  $\overline{DB} = \{DB^1, DB^2, ..., DB^n\}$  be a partition of DB into a partitions with sizes  $\overline{D} = \{D^1, D^2, ..., D^n\}$  respectively. An itemset is some  $X \subseteq I$ . Since identical itemsets exist for all nodes participating in all the methods described herein, we will denote them as  $X_1, X_2, ..., X_n$ . For any  $X_i$  and  $DB_i$ , let  $Support(X_i, DB_i)$  be the number of transactions in  $DB_i$  that contain all the items of  $DB_i$ . We call  $DB_i$  and  $DB_i$  support  $DB_i$  its global support.

For some user-defined support threshold 0 ≤ MinSup ≤ 1, we say that  $X_i$  is frequent iff  $Support(X_i, DB) \ge MinSup D$ and infrequent iff  $Support(X_i, DB) < MinSup D$ . We say  $X_i$  is locally frequent in the j partition iff  $Support(X_i, DB^j) \ge 1$  $MinSup D^{j}$ . Let  $X_{a}$ ,  $X_{p}$  be two frequent itemsets such that  $X_{p}$  $\subset$   $X_{a}$ , and let 0 < MinConf  $\leq$  1 be some user-defined confidence threshold. We say the rule  $r_{ap}$ :  $X_p \implies X_a \setminus X_p$  is confident iff  $Support(X_a, DB) \ge MinConf Support(X_p, DB)$ . The D-ARM problem addressed by preferred embodiments of the present invention is to distributively find all the rules of the form  $X \Rightarrow Y$ , while minimizing the amount of communication, well as as the number οf Support  $(\cdot, DB^1)$  is evaluated.

The messages the nodes send to one another are pairs  $\langle i, x_i^j \rangle$ , wherein i is an itemset (or rule) number, and  $x_i{}^j = \operatorname{Support}(X_i, DB^j)$ . We will assume that j, the origin of the message, can be inferred from information contained in the message, such as a message header. For each node p and itemset  $X_i$ , let  $G^p(X_i)$  be the group of all  $x_i{}^j$  such that  $\langle i, x_i^j \rangle$  was received by p. We will assume  $G^p(X_i)$  is equal for all p and refer to it as  $G(X_i)$ . D is either known to all nodes in advance or can be exchanged in the first p messages.

### SYSTEM AND METHODS

Fig. 1 is a schematic, pictorial illustration of a system 20 for distributed association rule mining (D-ARM), in accordance with a preferred embodiment of the present invention. System 20 comprises a plurality of computing nodes 22, connected by a communication network 24, typically a local area network (LAN) or system area network (SAN), as are known in the art. For simplicity of illustration, four nodes are shown, labeled A, B, C and D, although typically, a much larger number of nodes may be involved in D-ARM operations. Each node typically comprises a central processing unit (CPU), programmed in software to carry out the functions described hereinbelow. This software may be downloaded to nodes 22 in electronic form, over network 24, for example, or it may alternatively be supplied to the nodes on tangible media, such as CD-ROM. Each of the nodes has a local storage memory 26, such as a disk, which contains a

asynchronously, at each of nodes 22 that is participating in mining the database. As described below, the data contained in the messages, received in the process of Fig. 2B, serves as input to the computations performed in the process of Fig. 2A. At the same time, the state of the process of Fig. 2A determines how the incoming messages are treated in the process of Fig. 2B.

The basic idea behind the DDM method is to verify that an itemset is globally frequent before collecting its support counts from all nodes. This approach differs from FDM in that in DDM, the fact that an itemset is locally frequent in one partition is not considered sufficient evidence to trigger the collection of all the support counts of the itemset from all the nodes. Instead, the nodes perform a sort of negotiation, at the end of which they have decided which candidate itemsets are globally frequent and which are not. The support counts of the frequent itemsets are then collected optimally, with nocommunication wasted locally-frequent itemsets that are, nonetheless, globally infrequent.

Nodes 22 negotiate by exchanging messages containing local support counts for various itemsets. At any given point in the process of Fig. 2A, a common hypothesis H is shared by all nodes concerning the global support of each candidate itemset. As the nodes receive local support counts for an itemset, they adjust this hypothesis until it correctly predicts whether the itemset is frequent or infrequent. In addition, every node computes another private hypothesis P, based on the support counts already expressed by other nodes and the node's own local support count for each candidate itemset. For at least one node

partition of a database that is to be mined for association rules.

In order to carry out D-ARM operations, nodes 22 transmit and receive broadcast messages over network 24. Any suitable communication protocol may be used for this purpose, for example, an Ethernet (IEEE 802.3) or Fast Ethernet protocol, as are known in the art. Generally, these protocols generate frames of fixed size, typically 96 bytes for Fast Ethernet, or 1500 bytes for Ethernet, and any messages of greater length are broken up into multiple frames. As the number of nodes 22 in system 20, communication burden of D-ARM grows communication bandwidth linearly, and the typically becomes the chief bottleneck. In order to make the most efficient possible use of the available communication resources, nodes 22 preferably stack short broadcast messages together to fill up a frame. Such stacking is not essential to the operation of the present invention, however.

Figs. 2A and 2B are flow charts that schematically illustrate a method for D-ARM, referred to herein as the Distributed Decision Miner (DDM) method, in accordance with a preferred embodiment of the present invention. Fig. 2A illustrates a process by which each of nodes 22 generates broadcast messages to the other nodes, decides which candidate itemsets are globally frequent in the overall database contained in memories 26, computes the support for the candidate itemsets and, on the basis of the support, finds association rules. Fig. 2B shows how nodes 22 treat broadcast messages that they receive from the other nodes in the course of the process of Figs. 2A. The processes of Figs. 2A and 2B go on in parallel,

that has not yet expressed its local support count, and given any subset of the support counts for an itemset, the local hypothesis must correctly predict whether the itemset is frequent or infrequent. The defining assumptions regarding H and P are not required to hold for every node. Rather, it is enough that the assumption regarding H will hold eventually, and that the assumption regarding P holds for one node that has not yet expressed its support count.

The process of Fig. 2A uses the approach of the Apriori method described above to identify candidate itemsets of incrementally increasing size k. Initially, k is set to one, and  $C_1$  is set to be the set of all items i in I, at an initialization step 30. The set of nodes that have passed at this stage, Passed (as described further hereinbelow), is set to be the empty set. The nodes then begin to broadcast messages of the form  $\langle i, x_1^j \rangle$  on network 24, until they determine that all the nodes have passed, at a synchronization step 32.

In order to decide which messages to send, each node calculates the set of candidate itemsets  $X_i \in \mathcal{C}_k$  for which it has not yet expressed its local support count, at a candidate calculation step 34. For each such candidate, each node calculates the global hypothesis H and the local hypothesis P. If H and P at some node disagree on whether a candidate itemset is frequent or infrequent, then the node broadcasts its support count for that candidate, at a support broadcast step 36. The nodes broadcast their support counts at a certain rate, limited by the bandwidth of network 24, each message containing the support of one or several candidates chosen by the

node. No synchronization is required by these messages. Every time a node receives a message, it updates H and P for the candidate itemsets referred to in that message, as shown below in Fig. 2B.

If, for some node, H and P agree for every candidate itemset, that node has nothing to express and it passes on its turn, at a passing step 38. The node may later resume sending messages if arriving messages cause disagreement between H and P for some as-yet unexpressed candidate itemset. If a full round of passes was received from all parties, then H and P of all nodes agree on every candidate itemset, triggering the condition of step At this point, all nodes 22 must have the same set 32. of candidate itemsets,  $L_{\kappa}$ , at a candidate determination step 40:  $I_{ik}$  is simply the set of itemsets  $X_i$  $\in$   $C_k$  for which H now exceeds the predetermined minimum support level MinSup. This determination follows from definition of P, based on which there are two possibilities for each candidate itemset: either there is one node whose P correctly predicts the itemset size, or all the local support counts have been collected. In the former case, the H and P of the node whose P correctly predicts the itemset size must agree; and since all nodes compute the same H, that H must be correct for all nodes. In the latter case, H must be correct by definition.

Once  $L_k$  is known, all nodes 22 broadcast their support counts for any itemsets  $X_i$  in  $L_k$  that they did not broadcast previously, in a support collection step 42. This information is collected by the nodes for subsequent use. The Apriori procedure described above is then used to generate the collection of possible itemsets  $C_{k+1}$  for

the next iteration of the procedure, at an itemset generation step 44. In this step, candidate k+1-size itemsets are generated from the set of frequent k-size itemsets  $L_k$ . An itemset is included in  $C_{k+1}$  if and only if all its k-size subsets are in  $L_k$ .

The next iteration then commences at step 32, until  $C_{k+1}$  is found to be empty, at a termination step 46. At this point, the Apriori iteration ends, and all nodes have the same set of itemsets,  $L = \{L_1, L_2, ..., L_k\}$ , and the same support counts for all the itemsets. The nodes use this information to derive association rules, at a rule generation step 48, using any suitable procedure known in the art.

Fig. 2B shows how a given node 22 treats broadcast messages M that it receives from other nodes p, at a message reception step 50. The receiving node first checks whether the message is a "pass," at a pass checking step 52. If so, the receiving node adds p to the list of passed nodes, at a pass list compilation step 54. This list is consulted at a pass completion step 56 (which is essentially synchronization step 32, shown in Fig. 2A) to determine when all the nodes have passed. all the nodes have already passed, it means that message M must contain the support of one or more itemsets in Lx whose support p did not broadcast previously, and is now broadcasting at step 42 (Fig. 2A). In this case, the receiving node simply updates its corresponding support counts for these itemsets, at a support update step 58.

If at step 56 not all nodes have yet passed, it means that message M contains the support count for some itemset  $X_1 \in C_k$ , broadcast by p at step 36 (Fig. 2A). In

this case, the receiving node checks to determine whether it previously listed p in the set Passed, at a pass list checking step 62. If so, p is now removed from the set Passed, at a pass removal step 64. In either case, the receiving node recalculates the selection hypotheses H and P for itemset  $X_i$ , at a parameter recalculation step 66, and uses the new hypotheses in making its own broadcast decision about this itemset at step 34 (Fig. 2A).

Substantially any choice of functions H and P that satisfy the criteria defined above can be used in the DDM method. As an exemplary choice, we define H and P as follows:

$$H(X_i) = \begin{cases} 0 & G(X_i) = \phi \\ \frac{\sum_{x_i^p \in G(x_i)} x_i^p}{\sum_{x_i^p \in G(x_i)} D^p} \cdot D & \text{otherwise} \end{cases}$$
(1)

$$P(X_{i}, DB^{j}) = \sum_{x_{i}^{p} \in G(X_{i})} x_{i}^{p} + \frac{x_{i}^{j}}{D^{j}} \cdot \sum_{x_{i}^{p} \notin G(X_{i})} D^{p}$$
(2)

Some alternative formulations of H and P, which may also be useful in decision problems of other types, are described in Appendix A, hereinbelow. When estimating H, the nodes assume that the unexpressed support counts for each itemset are, on the average, the same as those already expressed. For P, on the other hand, each node assumes that those nodes that have not yet expressed

their local support counts for that itemset have the same relative support as it does itself.

Usually each node can choose which of candidate itemsets will have its support count sent next. Many heuristics can be used to break ties, for example: whenever two nodes are able to express the local support counts of the same candidate itemset, it is best if the node whose local support count will make a greater change in P expresses its support first. If there are opposing nodes for a candidate itemset (some of whose P is larger and others whose P is smaller than MinSup-D), then the one that makes the greater change has the better chance of "convincing" opposing nodes that they are wrong. If an opposing node's value of P is changed by the message to the extent that it now agrees with that of the sending node, the opposing node will refrain from expressing its own support and thus will save the cost of additional messages.

It is therefore a good strategy for a node to send those support counts which will cause the greatest change in the corresponding P hypothesis of opposing nodes. When node k expresses support for itemset  $X_i$ , the influence on P of party l is equal to  $\begin{vmatrix} x_i^k - \frac{x_i^l}{D^l} & D^k \end{vmatrix}$ . Since  $x_i^l$  has not yet been expressed, however, we estimate the change as a rating function:

$$R(X_i, DB^k) = \left| x_i^k - \frac{H(X_i)}{D} \cdot D^k \right|. \tag{3}$$

Any node thus breaks a tie by choosing to broadcast the support counts of those itemsets that have the maximal  $R(X_i,DB^j)$  value. Preferably, each node queues its itemsets for broadcasting according to their respective  $R(X_i,DB^j)$  values, updating the values (and the queue order) as it receives new support count data.

Table I below summarizes, in pseudocode form, the DDM method described above:

#### TABLE I - DISTRIBUTED DECISION MINER

For node j out of n:

- 1. Initialize  $C_1 = \{\{i\} : i \in I\}, k = 1, Passed = \emptyset$
- 2. While  $C_k \neq \emptyset$ 
  - (a) Do:
    - Choose an itemset  $X_i \in C_k$  that was not yet chosen and for which either  $H(X_1) < MinSup \le P(X_1, DB^j)$  or  $P(X_i, DB^j) < MinSup \le H(X_i)$ , and broadcast  $(i, Support(X_i, DB^j))$ .
    - If no such itemset exists, broadcast (pass).
  - (b) Until |Passed| = n.
  - (c)  $L_k = \{X_i \in C_k : H(X_i) \ge MinSup\}.$
  - (d) Broadcast the support counts for every  $X_i \in L_k$  that was never chosen.
  - (e)  $C_{k+1} = Apriori Gen(L_k)$ .
  - (f) k = k + 1.
- 3.  $Gen_Rules(L_1, L_2, ..., L_k)$ .

When node j receives a message M from node p:

1. If  $M - \langle pass \rangle$ , insert p into Passed.

- 2. Else if |Passed| = n, then M is the support counts of itemsets that p has not yet sent. Update counts accordingly.
- 3. Else  $M = \langle i, Support(X_i, DB^p) \rangle$ ;
  - If p ∈ Passed, then remove p from Passed.
  - Recalculate H(X<sub>i</sub>) and P(X<sub>i</sub>,DB<sup>1</sup>).

Figs. 3A-D, 4A-D and 5A-D are bar charts that schematically describe a running example of the DDM method for a single itemset, with four computing nodes 22, labeled A through D. Each set of bar charts reflects a subsequent point in the procedure. Sub-figures A through D at each point represent the state of calculations of H and P for the itemset at each of the corresponding nodes. MinSup is arbitrarily fixed at 20.

The nodes begin in Figs. 3A-D with local support counts 72 of 5, 7, 1 and 2, respectively. Each node calculates its private value 78 of P, based on its particular local support count. P in each case is based on a local guaranteed count 74 equal to the node's local count 72, plus local speculative counts 76 of the other nodes, which are assumed by the node (in the absence of evidence to the contrary) to be equal to the local count. At first, before any messages are exchanged, the itemset is considered infrequent because the global hypothesis H is zero. Nodes A and B disagree with this hypothesis, however, because their local (private) hypothesis P is that the itemset is frequent.

At some point, this disagreement causes node B to broadcast its local count. This changes both private value 78 of local hypothesis P and a global value 82 of

global hypothesis H at all the nodes, as shown in Figs. 4A-D. For each node other than B, value 78 includes local guaranteed count 74 plus a public guaranteed count 80, due to the support count broadcast by B, plus speculative counts 76. Global value 82 for all the nodes now includes public guaranteed count 80, plus global speculative counts 84 attributed to the other nodes. The local count of node B is marked as a public local count 86, to indicate that B should not broadcast this count again.

At this point, node A is satisfied that its local and global hypotheses agree (both being greater than MinSup), but for nodes C and D, the hypotheses now disagree. Therefore, node C broadcasts its local support count 72. The result is shown in Figs. 5A-5D. both nodes A and D, the global and local hypotheses agree. Since nodes B and C have already expressed their local counts, they accept the global hypothesis. itemset is now known to be infrequent, and no information will be transmitted with regard itemset, even though its exact support count remains unknown. The entire exchange has taken only two messages to complete, compared to six messages that would be required by FDM in order to reach the same conclusion.

Although the DDM method shown in Table I already reduces significantly the communication complexity of D-ARM, by comparison with methods known in the art, there are a number of ways in which it is possible to reduce the communication load still further. In this regard, it is often the case that partitions are not equally important. Typically, one partition may be exceptionally large and/or it may contain data that are more

significant, in that a frequent itemset is even more frequent in that partition. For example, if each partition contains the data from a different store, then partitions that belong to superstores are obviously more significant than those belonging to grocery stores.

It is therefore desirable that nodes that have more convincing evidence (extreme support counts) send their support counts at an earlier stage of the negotiation, due to the likelihood that their evidence will shorten negotiation time and reduce communication. Similarly, nodes that do not have convincing evidence preferably refrain from sending messages, so as not to use bandwidth that can be better employed by others. above, the rating function, given by equation (3)  $\mathbb{R}(X_i, DB^k) = \left| x_i^k - \frac{H(X_i)}{D} \cdot D \right|$ , gives the kth node an estimate of the effectiveness of each of its possible messages. Thus, it is preferable that the series of broadcast messages transmitted by the nodes have constantly-decreasing value of R. Generating such a series, however, requires that the nodes have global knowledge for weighing the importance of their possible messages.

For this purpose, an improvement to the DDM method is presented below in Table II. This improved method is referred to herein as the Freemptive Distributed Decision Miner (PDDM) method. It achieves a nearly-monotonically decreasing series of R values by selecting as a leader the node that has sent the message with the maximal R. Each node tracks the leader's identity and the R value of the last message sent by the leader. No other node is allowed to send messages unless the R value of its own

message is greater than that of the last message sent by the leader. If some other node sends a message with R greater than that of the leader, this node then replaces the leader.

TABLE II - PREEMPTIVE DISTRIBUTED DECISION MINER For node j out of n:

- 1. Initialize  $C_1 = \{\{i\} : i \in I\}, k = 1, Passed = \emptyset, leader = j, last <math>R = 0$ .
- 2. While  $C_k \neq \emptyset$ 
  - (a) Do:
    - Choose an itemset  $X_i \in C_k$  that was not yet chosen and for which either  $H(X_i) < MinSup \le P(X_i, DB^j)$  or  $P(X_i, DB^j) < MinSup \le H(X_i)$  and which maximizes  $R(X_i, DB^j)$ .
    - If such an itemset exists, and either  $R(X_1, DB^j) > last_R$ , or leader = j, broadcast  $\langle i, Support(X_i, DB^j) \rangle$ .
    - Else broadcast (pass).
  - (b) Until |Passed| = n.
  - (c)  $L_k = \{X_i \in C_k : H(X_i) \geq Minsup\}.$
  - (d) Broadcast the support counts for every  $X_i \in L_k$  that was never chosen.
  - (e)  $C_{k+1} = Apriori\_Gen(L_k)$ .
  - (f) k k + 1.
- 3.  $Gen_Rules(L_2, L_2, ..., L_k)$ .

When node j receives a message M from node p:

1. If  $M = \langle pass \rangle$ , insert p into Passed.

- 2. Else if | Passed| = n, then M is the support counts of itemsets that p has not yet sent. Update counts accordingly.
- 3. Else  $M = \langle i, Support(X_i, DB^p) \rangle$ :
  - If p & Passed, then remove p from Passed.
  - Recalculate  $H(X_i)$  and  $P(X_i, DB^i)$ .
  - If leader = p, then update last  $R = R(X_i, DB^p)$ .
  - Else if  $last_R < R(X_i, DB^j)$ 
    - Update last\_R =  $R(X_1, DB^n)$ .
    - Update leader = p.

Preventing other nodes from sending messages, as provided by PDDM. does not affect the correctness of the DDM method, because the method still terminates in the same state. It is important, however, that the leader hand the leadership on to another node when it decides to pass on its turn, since otherwise the method might not terminate. Hence, each time the leader passes on its turn, all nodes set the value of the leader's last R to zero. When the leader's last R is zero, any node that has any message to send may send it, and a node that has no message to send will pass on its turn.

It is easy for any node to calculate the leader's R value using equation (3). Optionally, R can be extended to include other properties of the message sent by the leader. For example, R can be used to encode information about the cost of sending the message, whether in terms of time (such as due to bandwidth restrictions) or money (when messages are sent, for instance, over a costly

wireless channel). The PDDM method tries to reach an R-optimal negotiation regardless of what R encodes.

It will be observed that in a highly-skewed database, PDDM reduces considerably the communication complexity of the basic DDM method described above. In balanced databases, the communication complexity is roughly unchanged, but PDDM imposes a small additional computational burden on the nodes.

Whereas the DDM and PDDM methods described above improving the communication efficiency focus on finding itemsets with sufficient support, the ultimate object of ARM is to find association rules that not only have support greater than MinSup, but which also have confidence greater than MinConf. It is not necessary to calculate the exact support or confidence of the rules, but only to verify that they exceed the predetermined thresholds. This observation allows simplification of the communication process. illustrated by the following two examples:

1. Assume that Parmesan. PastaSauce and Parmesan ∧

PastaSauce are all globally frequent. The rule

PastaSauce ⇒ Parmesan should thus be considered.

Assume also that this rule is locally frequent in

every partition, but confident in none (i.e.,

Support(Parmesan ∧ PastaSauce, DBP)

 $\frac{Support(Parmesan \land PastaSauce, DB^p)}{Support(PastaSauce, DB^p)} < \lambda \quad \text{for all p)}.$ 

Using DDM, three messages are required to determine that both  $Parmesan \land PastaSauce$  and PastaSauce are significant (compared to 6n messages in FDM). Using DDM and PDDM, an additional 3(n-1) messages would be needed to collect the local support counts of the

remaining nodes for Parmesan  $\wedge$  Pastasauce and PastaSauce before judging whether Pastasauce  $\Rightarrow$  Parmesan is significant. Note, however, that if there is no node at which the local confidence of this rule is above  $\lambda$ , then the global confidence cannot be above  $\lambda$ . By implementing an appropriate decision criterion, this rule could have been pruned without sending a single message.

2. Assume that this same rule is both supported and confident in every partition. If one node suggests that the rule is globally confident, and no other node objects, this information is sufficient to determine that the rule is indeed globally significant.

Figs. 6A and 6B are flow charts that schematically illustrate a method for D-ARM based on these observations, in accordance with a preferred embodiment of the present invention. The method is referred to herein as the Distributed Dual Decision Miner (DDDM) and is shown in pseudocode form in Table III below.

In the first phase of this method, shown in Fig. 6A, itemsets with support above MinSup are collected into a set  $L = \{L_2, L_2, ..., L_k\}$ , substantially as described above. Either the DDM or the PDDM method may be used for this purpose. It will accordingly be observed that Fig. 6A is substantially similar to Fig. 2A, up through step 46, except that step 42 is eliminated here. Because of the improved method introduced here for mining association rules with high confidence, which is performed at a mining step 90, there is no need for all the nodes to broadcast their support counts for all the itemsets in L.

The method by which nodes 22 process the broadcast messages that they receive is substantially identical to that shown in Fig. 2B.

TABLE III - DISTRIBUTED DUAL DECISION MINER

For node j out of n:

- 1. Initialize  $C_1 = \{\{i\} : i \in I\}, k = 1, Passed = \emptyset$
- 2. While  $C_k \neq \emptyset$ 
  - (a) Do:
    - Choose an itemset  $X_i \in C_k$  that was not yet chosen and for which either  $H(X_i) < MinSup \le P(X_1, DB^1)$  or  $P(X_i, DB^j) < MinSup \le H(X_i)$ , and broadcast  $\langle i, Support(X_i, DB^j) \rangle$ .
    - If no such itemset exists, broadcast (pass).
  - (b) Until |Passed| = n.
  - (c)  $L_k = \{X_i \in C_k : H(X_i) \geq MinSup\}.$
  - (d)  $C_{k+1} = Apriori\_Gen(L_k)$ .
  - (c) k = k + 1.
- 3. Mine Rules  $(L_1, L_2, ..., L_k)$ .

When node j receives a message M from node p:

- 1. If  $M = \langle pass \rangle$ , insert p into Passed.
- 2. Else if |Passed| = n, then M is the support counts of itemsets that p has not yet sent. Update counts accordingly.
- 3. Else  $M = \langle i, Support(x_1, DB^p) \rangle$ :
  - If  $p \in Passed$ , then remove p from Passed.
  - Recalculate H(X<sub>i</sub>) and P(X<sub>i</sub>, DB<sup>j</sup>).

At step 90, nodes 22 mine L to find rules whose confidence is greater than a user-defined threshold  $\lambda$ . This method, referred to herein as the Distributed Decision Confidence Miner (DDCM) is shown in Fig. 6B, and is also listed below in pseudocode form in Table IV. It corresponds to the step "Mine\_Rules( $L_1$ ,  $L_2$ , ...,  $L_k$ )" in Table III.

At the outset of DDCM, each node 22 constructs the set of all rules  $R_1$  supported by L, at a rule initialization step 92. As listed in Table IV,  $R_1$  contains all rules  $r_k$  of the form  $X_p \Rightarrow X_a \backslash X_p$  such that  $X_p$ ,  $X_a \in L$  and  $X_p \subset X_a$ . A set of Passed nodes, which is initially empty, is used here as in the DDM method. DDCM continues iteratively to evaluate rules  $r_k$  and to collect their support until all nodes have passed, at a rule synchronization step 94.

DDCM then makes one round of negotiations among nodes 22 to decide which of the candidate rules  $r_k$  satisfy the condition that  $Support(X_a, DB) \geq \lambda \cdot Support(X_p, DB)$ . the course of this negotiation, each node 22 determines which rules are likely to influence this decision, at a candidate rule selection step 96. The determination is based on global and local rule hypothesis criteria, H and are conceptually similar which to the hypothesis criteria used at step 34. As in the case of the basic DDM method, a range of different choices of Hand P may be used here, as well. Exemplary hypothesis functions are defined by equations (4) and (5) below. For simplicity of notation, we represent the rule  $x_p \Rightarrow$  $X_{a} \setminus X_{p}$  as  $r_{ap}$  and define the group of rules  $G(r_{ap})$  as

 $G(r_{ap}) = \{j : x_p^j \in G(X_p) \land x_a^j \in G(X_a)\}, \text{ wherein } G(X_p) \text{ and } G(X_a) \}$  are the corresponding groups of itemsets.

$$P(r_{ap}) = \frac{\sum_{l \in G(r_{ap})} x_a^l + (n - |G(r_{ap})|) \cdot x_a^l}{\sum_{l \in G(r_{ap})} x_p^l + (n - |G(r_{ap})|) \cdot x_p^l}$$
(4)

$$H(X_i) = \begin{cases} \frac{\sum_{l \in G(x_{ap})} x_{al}^{l}}{\sum_{l \in G(x_{ap})} x_{p}^{l}} & G(x_{ap}) > 0 \\ 0 & \text{otherwise} \end{cases}$$
 (5)

For each node 22, a given rule  $r_{\rm RP}$  will be selected at step 96 if the values of H and P calculated by this node for this rule disagree as to whether or not the confidence of the rule is above the threshold  $\lambda$ . a rule exists, and node 22 has not previously broadcast the support of either or both of  $X_a$  and  $X_p$ , the node the as-yet unbroadcast support, broadcasts broadcasting step 98. The node thus sends a message of one of three types:  $\left\langle k, x_p^i, x_a^i \right\rangle$ ,  $\left\langle k, x_p^i \right\rangle$ , or  $\left\langle k, x_a^i \right\rangle$ , depending on the choice of support counts to be expressed, wherein k is the number of the rule in some deterministic enumeration. A ranking function R may be defined, as in to determine the order in which the node will choose the rules for broadcast, for example:

$$R(x_{ap}, DB^{i}) = \begin{vmatrix} x_{a}^{i} - \frac{H(X_{a})}{D} & D^{i} \\ x_{p}^{i} - \frac{H(X_{p})}{D} & D^{i} \end{vmatrix}$$
 (6)

When node 22 has no more rules remaining that meet the criteria of step 96, it broadcasts a pass message, at a pass broadcast step 100.

At the same time as nodes 22 transmit messages in steps 96 through 100, they also receive the messages that are broadcast by the other nodes. The nodes handle these messages in a manner similar to that shown in Fig. 2B. Whenever one of the nodes receives a broadcast message containing another node's support count for some rule  $r_{\rm sp}$ , it uses the support count to recalculate  $G(r_1)$  for every rule  $r_1$  that includes either  $X_a$  or  $X_p$ . If  $G(r_1)$  changes as a consequence, the node then updates  $H(r_1)$  and  $P(r_1)$  accordingly, for subsequent use at step 96.

Once all the nodes have passed at step 94, each node can compute the complete set  $R_{\rm T}$ , containing the rules  $r_k$  from the original set  $R_{\rm I}$  that have been found to have confidence greater than the threshold  $\lambda$ , at a mining completion step 102. At this point, the global hypotheses H of all the nodes will have converged, so that the members of  $R_{\rm T}$  are simply those rules for which  $H(r_k) \geq \lambda$ .

TABLE IV - DISTRIBUTED DECISION CONFIDENCE MINER For node i of n nodes:

- 1. Initialize
- $R_1$  to be the set of all rules  $X_p \Rightarrow X_n \backslash X_p$  such that  $X_p$ ,  $X_3 \in L$  and  $X_p \subset X_a$ .

- $Passed = \emptyset$ .
- 2. Do:
- Choose  $r_k$  to be some  $X_p \Rightarrow X_k \setminus X_p \in R_1$  such that  $i \neq G(r_k)$ , and either  $H(r_k) < \lambda \leq P(r_k, DB^i)$  or  $P(r_k, DB^i) < \lambda \leq H(r_k)$ .
  - $\begin{array}{lll} & \text{If both } Support(X_p,DB^i) & \text{and } Support(X_a,DB^i) \\ & \text{were} & \text{not} & \text{sent,} & \text{broadcast} \\ & & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\ & &$
  - If  $Support(X_p, DB^i)$  was already sent, broadcast  $\left\langle k, Support(X_a, DB^i) \right\rangle$ .
  - If  $Support(X_a, DB^i)$  was already sent, broadcast  $\langle k, Support(X_p, DB^i) \rangle$ .
- If there is no such  $r_k$ , broadcast (pass).
- 3. Until |Passed| = n.
- $4 \;. \quad \mathcal{R}_T \;=\; \big\{ x_k \;\in\; \mathcal{R}_{\mathcal{I}} \;:\; H(x_k) \;\geq\; \lambda \big\}.$

When node i receives a message M from node j:

- 1. If  $M = \langle pass \rangle$ , insert p into Passed.
- 2. Else  $M = \langle k, Support(X_p, DB^j), Support(X_a, DB^j) \rangle$ .
  - If j c Passed, then remove j from Passed.
  - Recalculate  $G(r_1)$  for every  $r_1$  that includes  $X_3$  and/or  $X_{p_1}$  if  $G\setminus (r_1)$  changes, update  $H(r_1)$  and  $P(r_1)$ , as well.

The number of rules that can be generated from a given set of frequent itemsets is enormous. In order to check all the potential rules induced by a single k-size

frequent itemset X, it is necessary to check every rule  $X_p$   $\Rightarrow X_n \backslash X_p : X_p \subset X_a \subseteq X$ . This is a total of  $\sum_{i=1}^k \binom{k}{i} \sum_{j=1}^i \binom{i}{j} = 3^k \text{ potential rules.}$  It is possible,

however, to prune the rules in advance using the following observation: If  $X_p$  and  $X_a$  are two itemsets, such that  $X_p \subset X_a$ , and the confidence of  $X_p \Rightarrow X_a \backslash X_p$  is below the MinConf threshold, then for any  $X_{pp} \subset X_p$ , the confidence of  $X_{pp} \Rightarrow X_a \backslash X_{pp}$  is also below MinConf. Similarly, for any  $X_{aa} \supset X_a$ , the confidence of  $X_p \Rightarrow X_{aa} \backslash X_p$  is below MinConf. This observation is correct because  $Support(X_p, DB) \leq Support(X_{pp}, DB)$ , and  $Support(X_{aa}, DB) \leq Support(X_a, DB)$ . If, on the other hand, the rule  $X_p \Rightarrow X_a \backslash X_p$  is confident, then for every  $X_p \subset X_{pp} \subset X_{aa} \subseteq X_a$ , the rule  $X_{pp} \Rightarrow X_{aa} \backslash X_{pp}$  is confident as well.

This observation allows us to alter the DDCM method of Table IV by splitting it into several rounds. improved method, referred to herein as the Pruning Distributed Decision Confidence Miner (PDDCM), is shown below in Table V. At each round of the PDDCM method, many of the possible rules can either be pruned or inferred with no communication. ₩e initialize the candidate rule set  $R_k$  with a single rule  $R_0 = \{\emptyset \Rightarrow \emptyset\}$ , which must be both supported and confident. In each round, nodes 22 run a procedure similar to DDCM to decide which of the rules in  $R_k$  are confident. The nodes develop new candidate rules according to the following two candidate generation methods: If a rule rk is found to be confident, then every rule that specifies the precedent

or generalizes the antecedent of  $r_k$  must also be confident, and every rule that further specifies the antecedent is considered a candidate. If, on the other hand, a rule is found not to be confident, another rule that specifies its precedent may still be a candidate.

TABLE V - PRUNING DISTRIBUTED DECISION CONFIDENCE MINER

Definition: For some  $X \in L_k$ , specifiers(X) =

$$\{X^i\in L_{k+1}\,:\,X\subset X^i\},$$

For node i of n nodes:

- 1. Initialize  $R_0 = \{\emptyset \Rightarrow \emptyset\}$ , k = 0,  $R = \emptyset$ .
- 2. While  $R_k \neq \emptyset$ 
  - (a) Initialize Passed = Ø.
  - (b) Do:
    - Choose  $r_1$  to be some  $X_p \Rightarrow X_A \setminus X_P \in \mathbb{R}_k$  such that  $i \not\sim G(r_1)$ , and either  $H(r_1) < \lambda \leq P(r_1, DB^i)$  or  $P(r_1, DB^i) < \lambda \leq H(r_1)$ .
      - If both  $Support(X_p, DB^i)$  and  $Support(X_a, DB^i)$  were not sent, broadcast  $\Big\langle k, Support(X_p, DB^i), Support(X_a, DB^i) \Big\rangle$ .
      - If  $Support(X_p, DB^i)$  was already sent, broadcast  $\langle k, Support(X_a, DB^i) \rangle$ .
      - If  $Support(X_2,DB^i)$  was already sent, broadcast  $\langle k, Support(X_p,DB^i) \rangle$ .
    - If there is no such  $r_k$ , broadcast  $\langle pass \rangle$ .
  - (c) Until |Passed| = n.

(d) For each  $r_1 = X_p \Rightarrow X_a \setminus X_p \in R_k$  such that  $H(r_1) < MinConf$ :

 $R_{k+1} = R_{k+1} \cup \{X_{pp} \Rightarrow X_a \setminus X_{pp} : X_{pp} \in \operatorname{specifiers}(X_p)\}$ 

- (e) For each  $x_1 = X_p \Rightarrow X_a \backslash X_p \in R_k$  such that  $H(x_1) \geq MinConf$ :
  - $R_{k+1} = R_{k+1} \cup \{X_p \Longrightarrow X_{\alpha\alpha} \setminus X_p : X_{p\sigma} \in \operatorname{specifiers}(X_a)\}$
  - $R_T = R_T \cup \{X_{pp} \Rightarrow X_{aa} \setminus X_{pp} : X_p \subseteq X_{pp} \subset X_{aa} \subseteq X_a\}$
- (f) k k + 1.

When node i receives a message M from node j:

- 1. If  $M = \langle pass \rangle$ , insert p into Passed.
- 2. Else  $M = \langle k, Support(X_p, DB^j), Support(X_a, DB^j) \rangle$ .
  - If  $j \in Passed$ , then remove j from Passed.
  - Recalculate  $G(r_1)$  for every  $r_1$  that includes  $X_n$  and/or  $X_p$ ; if  $G\setminus (r_1)$  changes, update  $H(r_1)$  and  $P(r_1)$ , as well.

The inventors have tested the methods of the present invention on synthetic databases, generated using the "gen" tool, which is available at www.almaden.ibm.com/cs/quest. The results have been compared with those obtained by processing the same databases using the CD and FDM algorithms described in the Background of the Invention. The number of bytes that must be transmitted to find association rules using CD or FDM grows rapidly as the value of Minsup or the number of computing nodes n increases. The growth is considerably slower when the methods of the present invention are used, with DDDM giving the best performance

on unskewed databases. In heavily-skewed databases, PDDM is substantially better than DDM. A method combining the features of DDDM and PDDM would likely give the best overall performance.

The methods described hereinabove may be used to address substantially any D-ARM problem, but they are particularly advantageous in applications involving a large number of widely-distributed computing nodes. For example, these methods may be used to mine peer-to-peer systems, for purposes such as finding associations between the MP3 files of different Napster users (more than 1.5 million files in about 10,000 libraries No method known in the art can cope with n=present). 10,000 with the Internet communication speed available today. As another example, the methods of the present invention may be used for broad-scale parallelization of data mining, splitting the problem until each partition fits into the memory of a conventional personal computer. In addition, these methods are particularly useful environments in which communication bandwidth is at a premium, such as billing centers for large communication providers. Although these billing centers usually have fast and wide-ranging networks, data mining is performed in such centers as an auxiliary task, and the resources it consumes come at the expense of the main system activity.

Although the preferred embodiments described above are directed to count distribution (CD) type approaches to D-ARM, the principles of the present invention may also be applied, mutatis mutandis, to approaches of other types, such as data distribution (DD) approaches, as described in the above-mentioned article by Agrawal and

shafer. Similarly, although these preferred embodiments are based on certain characteristics of common networks and computing systems, such as broadcast support, for example, the methods of the present invention are not inherently dependent on particular system or network characteristics, and may therefore be adapted to work in substantially any distributed computing environment.

It will thus be appreciated that the preferred embodiments described above are cited by way of example, and that the present invention is not limited to what has particularly shown and described hereinabove. Rather, the scope of the present invention includes both combinations and subcombinations of the various features described hereinabove, well variations as as modifications thereof which would occur to skilled in the art upon reading the foregoing description and which are not disclosed in the prior art.

## APPENDIX A - H AND P FOR OTHER TARGET FUNCTIONS

DDM can be applied to a variety of decision problems. A sequential decision problem can be written as  $f:x,\delta\to\{0,1\}$ , where x is some arbitrary measure and  $\delta$  is a threshold which is provided by the user. In the distributed form of a decision function we assume that the measure is the average (or the sum) of N measures, each held by a different computing node. Hence,

$$g: \overset{\sim}{\times}, \delta \rightarrow \{0,1\} = f: \frac{1}{N} \sum_{i=1}^{N} x_i, \delta \rightarrow \{0,1\}.$$

In the preferred embodiments of the present invention described above, the hypothesis functions H and P are defined in terms of two target functions:

$$f_{support}(x, Minsup) = \begin{cases} 0 & x < Minsup \\ 1 & x \ge Minsup \end{cases}$$

and

$$f_{confidence}(\langle x, y \rangle, MinConf) = \begin{cases} 0 & \frac{x}{y} < MinConf \\ 1 & \frac{x}{y} \ge MinConf \end{cases}$$

Here we will show that the same algorithm can be applied (i.e., H and P can be defined) for two other target functions: The variance and the entropy  $h_Z$ . Both target functions are defined on distributions, which can be referred to as vectors of values.

The H function will, in both cases, have the same rationale as in the case of  $f_{support}$  and  $f_{confidence}$ ; the

nodes will assume that the partial information published at each stage of the algorithm correctly represents the distribution. As for the P function, it becomes a little more complicated because the upper bound and the lower bound are calculated using different formulas. Also, they require the computation of the smoothest possible distribution (hence SPD), given a partial group of the distribution vectors. For k=2 the solution is simple:

• If 
$$x_0^x+\sum_{i\in G}x_0^i<\frac{1}{2}$$
 and  $x_1^x+\sum_{i\in G}x_1^i<\frac{1}{2}$  - the SPD is  $\left(\frac{1}{2},\frac{1}{2}\right)$ 

• If 
$$x_0^r + \sum_{i \in G} x_0^i > \frac{1}{2}$$
 - the SPD is 
$$\left( x_0^r + \sum_{i \in G} x_0^i, 1 - x_0^r - \sum_{i \in G} x_0^i \right)$$

• If 
$$x_1^r + \sum_{i \in G} x_1^i > \frac{1}{2}$$
 - the SPD is 
$$\left(1 - x_1^r - \sum_{i \in G} x_1^i, x_1^r + \sum_{i \in G} x_1^i\right)$$

For k larger than 2 the computation of the SPD can be computed by an algorithm which has complexity linear in k.

## VARIANCE:

The variance target function is defined as  $f_{\text{Var}} \left( X, \, \sigma^2 \right) = \begin{cases} 0 & \text{Var}(X) < \sigma^2 \\ 1 & \text{Var}(X) \ge \sigma^2 \end{cases}, \text{ where } X = \left\{ x_1, \, x_2, \, \dots, \, x_k \right\} \text{ is a}$ 

distribution measure. The H function will have the same rationale as in the case of the support and confidence target functions, it will assume that the data already sent represents the data that was not sent. Hence, given  $X_G$  - a partial group of  $X^i$  vectors, sent by part of the

nodes  $H(X_G) = \begin{cases} 0 & |X_G| = 0 \\ Var \left(\frac{1}{|X_G|} \sum_{X^1 \in X_G} X^1\right) & \text{otherwise}; \end{cases} \text{ where}$ 

 $\frac{1}{|X_{\mathcal{G}}|} \sum_{\chi^i \in X_{\mathcal{G}}} \chi^i$  is the piecewise average distribution. Each

node r will also compute:

$$P(X_G, X^F) = \begin{cases} H(X_G) & X^F \in X_G \\ Vax \left(\frac{1}{N} \left[ (N - |X_G|) X^F + \sum_{X^i \in X_G} X^i \right] \right) & H(X_G) > \sigma^2 \end{cases}$$

$$Vax(SPD(X_G)) & H(X_G) \leq \sigma^2$$

## BINARY ENTROPY:

The binary entropy target function is defined as  $f_{h_2}(X,\gamma) = \begin{cases} 0 & h_2(X) < \gamma \\ 1 & h_2(X) \ge \gamma \end{cases}, \text{ where } X = \{x_1, x_2, \dots, x_k\} \text{ is a partial of the property of th$ 

distribution measure. The H function will have the same rationale as in the case of the support and confidence target functions, it will assume that the data already sent represents the data that was not sent. Hence, given  $X_C$  - a partial group of  $X^i$  vectors, sent by part of the

nodes, 
$$H(X_G) = \begin{cases} 0 & |X_G| = 0 \\ h_2 \left(\frac{1}{|X_G|} \sum_{X^i \in X_G} X^i\right) & \text{otherwise} \end{cases}$$
 where

 $\frac{1}{\left|X_{G}\right|}\sum_{X^{i}\in X_{G}}X^{i}$  is the piecewise average distribution. Each

node r will compute:

$$P(X_G, X^r) = \begin{cases} H(X_G) & X^r \in X_G \\ h_2\left(\frac{1}{N}\left[(N - |X_G|)X^r + \sum_{X^i \in X_G} X^i\right]\right) & H(X_G) < \gamma^2 \\ h_2(SPD(X_G)) & H(X_G) \ge \gamma^2 \end{cases}$$